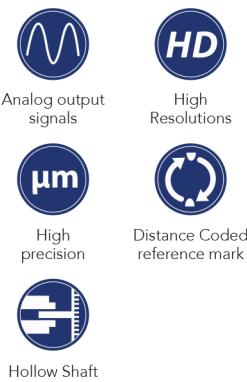
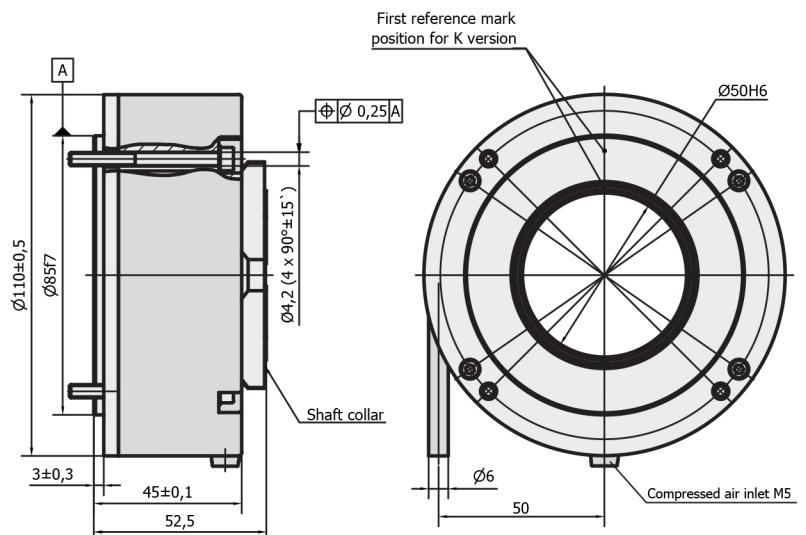
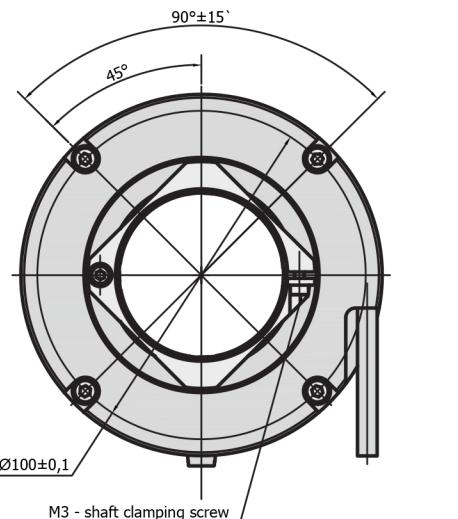


PHOTOELECTRIC ANGLE ENCODER

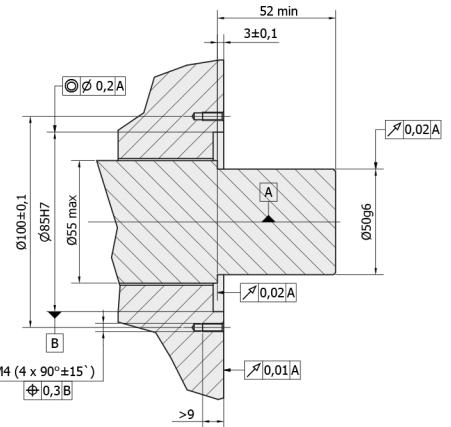
A110H



A110H is a photoelectric hollow shaft angle encoder that produces up to 1.800.000 output pulses per revolution and has the accuracy of ± 5 arc. sec.



MOUNTING REQUIREMENTS



MECHANICAL DATA

Line number on disc (Z)	18000
Number of output pulses per revolution	Z x k, where k = 1, 2, 3, 4, 5, 8, 10, 20, 25, 50, 100 (k - interpolation factor)
Reference signal: - standard (S) - distance-coded (K)	One per shaft revolution 36 per shaft revolution
Permissible mech. speed	≤ 3000 rpm
Max. operating speed (depends on number of output pulses)	600 to 1000 rpm
Accuracy grades:	± 5.0 arc. sec
Permissible shaft runout: - axial	0.02 mm
- radial	0.05 mm
Starting torque at 20°C	≤ 0.08 Nm
Rotor moment of inertia	$< 0.6 \times 10^{-4}$ kgm²
Protection (IEC 529)	IP64
Maximum weight without cable	1.2 kg
Operating temperature	0...+70°C
Storage temperature	-30...+85°C
Maximum humidity (non condensing)	98 %
Permissible vibration	≤ 100 m/s²
Permissible shock (6 ms)	≤ 300 m/s²

ELECTRICAL DATA

Version	A110H-A ~ 11 μApp	A110H-AV ~ 1 Vpp	A110H-F □ TTL
Supply voltage (U_p)	+5 V ± 5%	+5 V ± 5%	+5 V ± 5%;
Max. supply current (without load)	100 mA	120 mA	120 mA
Light source	LED	LED	LED
Incremental signals	Two sinusoidal I_1 and I_2 . Amplitude at 1 kΩ load: - $I_1 = 7\text{-}16 \mu\text{A}$ - $I_2 = 7\text{-}16 \mu\text{A}$	Differential sine +A/-A and +B/-B. Amplitude at 120 Ω load: - A = 0.6-1.2 V - B = 0.6-1.2 V	Differential square-wave U1/̄U1 and U2/̄U2. Signal levels at 20 mA load current: - low (logic "0") ≤ 0.5 V - high (logic "1") ≥ 2.4 V
Reference signal	One quasi-triangular I_0 peak per revolution. Signal magnitude at 1 kΩ load: - $I_0 = 2.8 \mu\text{A}$ (usable component)	One quasi-triangular +R and its complementary -R per revolution. Signals magnitude at 120 Ω load - R = 0.2-0.8 V (usable component)	One differential square-wave U0/U0 per revolution. Signal levels at 20 mA load current: - low (logic "0") < 0.5 V - high (logic "1") > 2.4 V
Fault detection signal Ūs	- no error occur - error occur	- one square-wave pulse high low	- one square-wave pulse high low
Maximum operating frequency	(-3 dB) ≥ 160 kHz	(-3 dB) ≥ 180 kHz	160-2000 kHz (depends on interpolation factor)
Direction of signals	I_2 lags I_1 for clockwise rotation (viewed from shaft side)	+B lags +A for clockwise rotation (viewed from shaft side)	U2 lags U1 with clockwise rotation (viewed from shaft side)
Maximum rise and fall time	-	-	< 0.5 μs
Standard cable length	1 m, without connector	1 m, without connector	1 m, without connector
Maximum cable length	5 m	25 m	25 m
Output signals			

Note:

1. Maximum working rotation speed (with proper encoder counting) is limited by maximum operating frequency and maximum mechanical rotation speed.
2. If cable extension is used, power supply conductor cross-section should not be smaller than 0.5 mm².

ACCESSORIES

CONNECTORS FOR CABLE	B12 12-pin round connector	C9 9-pin round connector	C12 12-pin round connector	D9 9-pin flat connector	D15 15-pin flat connector	RS10 10-pin round connector	ONC 10-pin round connector
DIGITAL READOUT DEVICES	CS3000					CS5500	
COUPLING				SC70			
EXTERNAL INTERPOLATOR				NK			

ORDER FORM

A110H - X1 - X2 - X3 - X4/X5

Output signal version (X1):	Pulse number per revolution (X2):	Reference signal (X3):	Cable Length (X4):	Connector type (X5):
A AV F	18000 ... 1800000*	S - one per revolution K - 36 per revolution, distance-coded	AR01 - 1m AR02 - 2m AR03 - 3m	W - without connector B12 - round, 12 pins C9 - round, 9 pins C12 - round, 12 pins D9 - flat, 9 pins D15 - flat, 15 pins RS10 - round, 10 pins ONC - round, 10 pins

ORDER EXAMPLE: 1) A110H-A-18000-K-AR01/W-0